

# Introduction to Phase-field Modeling in Computational Mechanics

in computational mechanics

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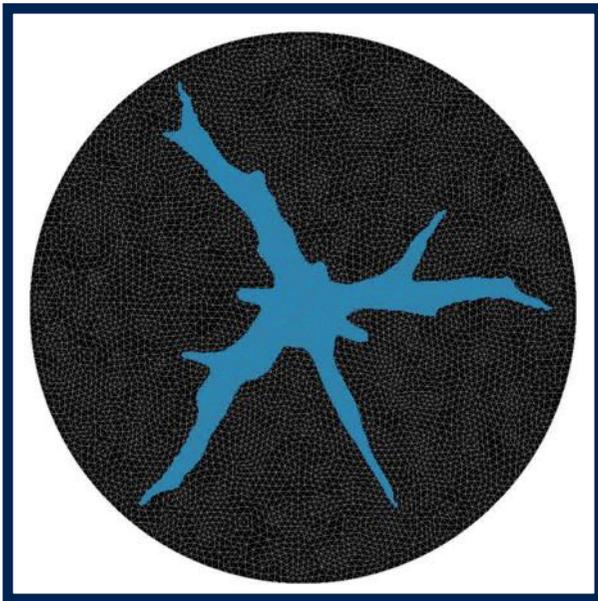
Penn State University - Teaching Seminar

# Motivation : problems with interfaces

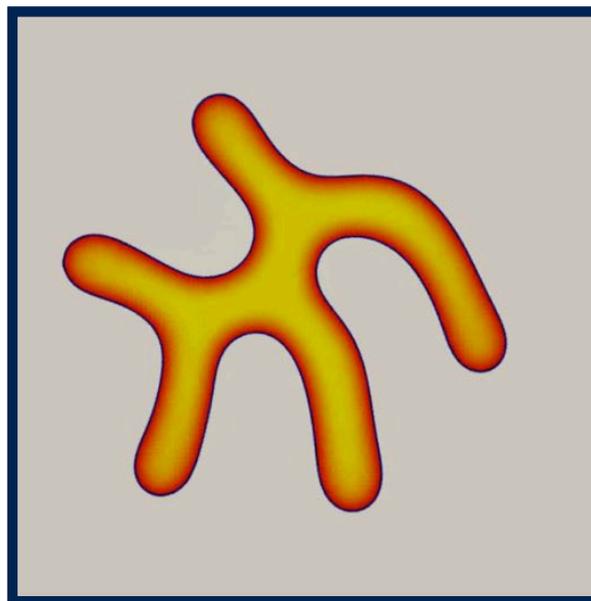
Two phases can be identified

Interface is complex and evolves

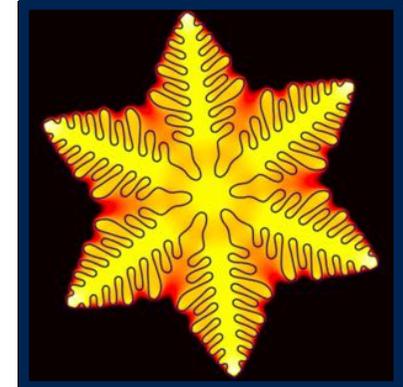
**Fracture**



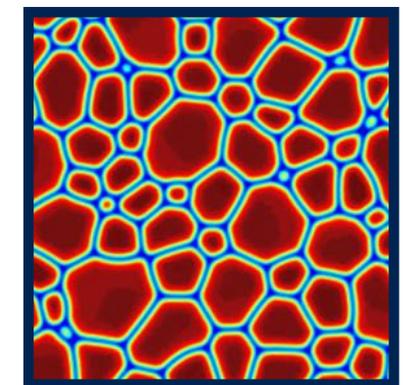
**Membranes**



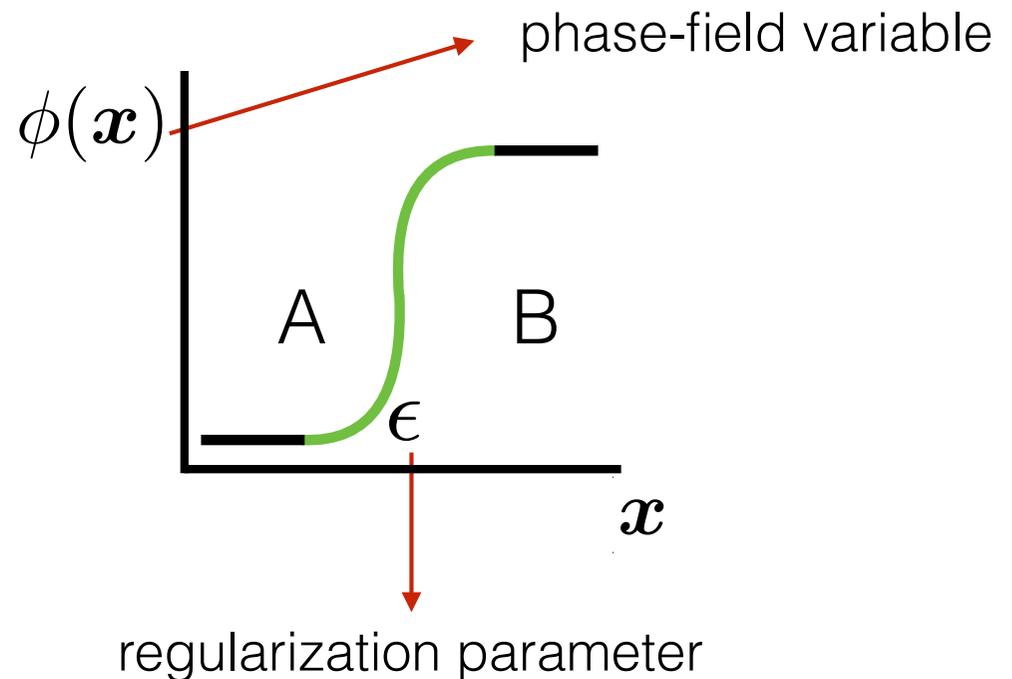
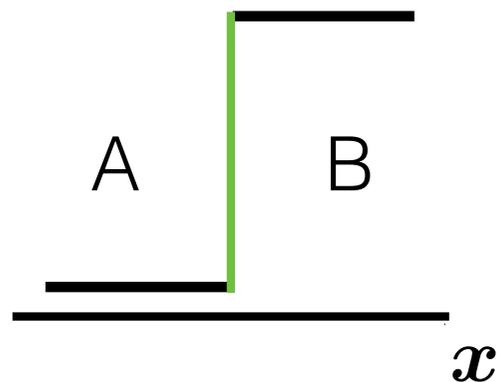
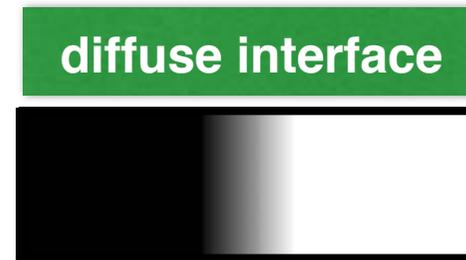
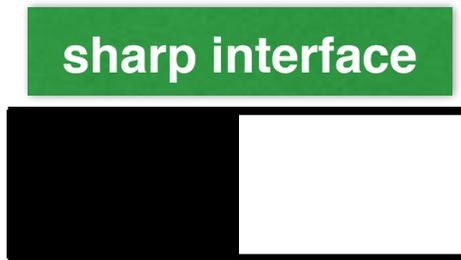
**Solidification**



**Microstructure**



# Phase-field Modeling Basics

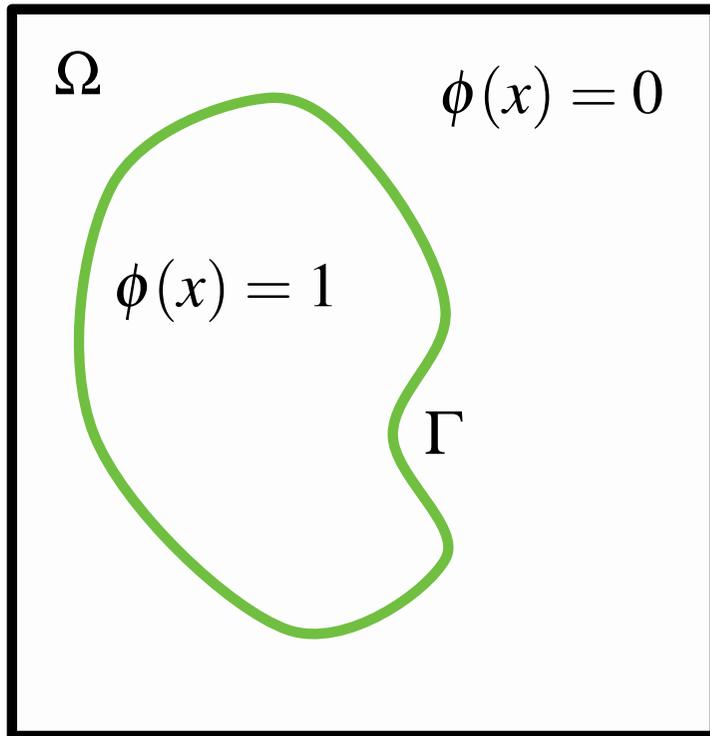


Continuous on the domain  
Avoid interface tracking



Can we rewrite our sharp  
interface model in terms of  
the phase-field?

# Phase-field and Geometry



**Volume**

$$\int_{\Omega} \phi \, d\Omega$$

**Area**

$$\int_{\Omega} \left[ \varepsilon |\nabla \phi|^2 + \frac{1}{\varepsilon} F(\phi) \right] d\Omega$$

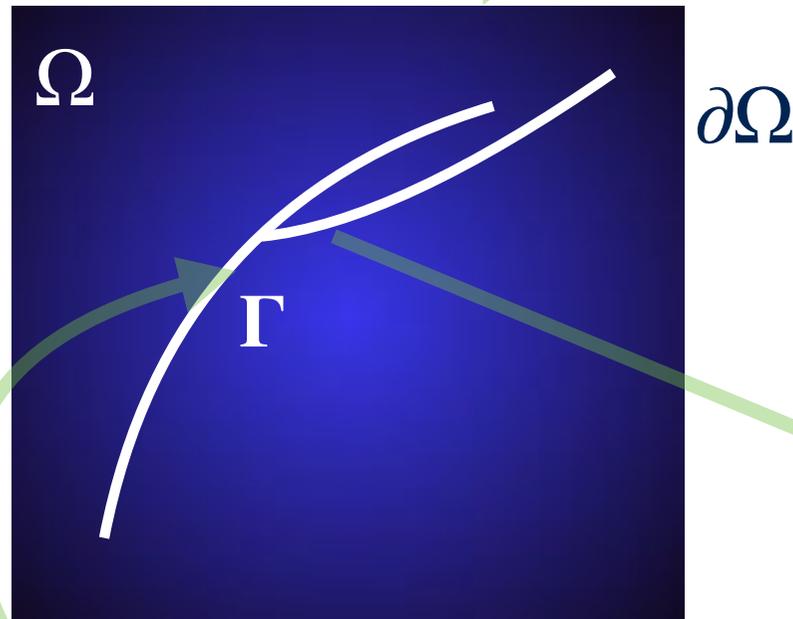
**Curvature**

$$\varepsilon \Delta \phi + \frac{1}{\varepsilon} F(\phi)$$

# Brittle Fracture: Sharp Interface Approach

Linear Elastic Solid

$$W = E(u) : \mathbb{C} : E(u)$$



Boundary conditions

$$u = u^* \text{ on } \partial\Omega_u$$

$$\sigma \cdot n = t^* \text{ on } \partial\Omega_t$$

Boundary condition

$$\sigma \cdot n = 0 \text{ on } \Gamma$$

**Interface behavior**

$$f(G_c)$$

# Brittle Fracture : Phase-field Model Derivation

Linear Elastic Solid

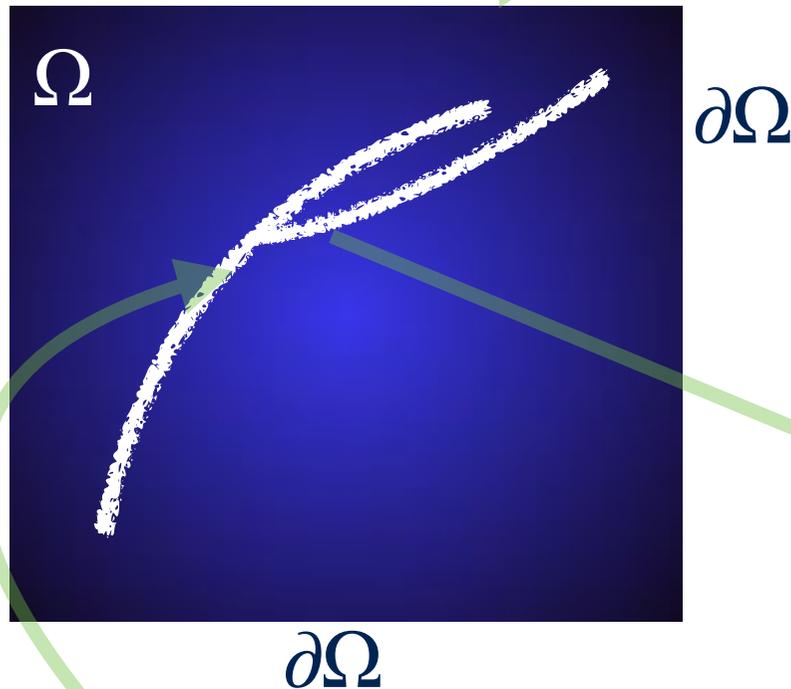
$$W = (1 - \phi)^2 E(u) : \mathbb{C} : E(u)$$

Boundary conditions

$$u = u^* \text{ on } \partial\Omega_u$$

$$\sigma \cdot n = t^* \text{ on } \partial\Omega_t$$

fracture  
 $\phi(x) = 1$   
 undamaged  
 $\phi(x) = 0$



~~Interface behavior~~



**Phase-field PDE**

~~Boundary condition~~

~~$\sigma \cdot n = 0 \text{ on } \Gamma$~~

# Brittle Fracture : Phase-field Model Derivation

$$\Psi(u, \phi) = \underbrace{(1 - \phi)^2 E(u) : \mathbb{C} : E(u)}_{\text{elastic energy}} + \underbrace{G_c \left( \frac{\phi^2}{2\varepsilon} + \frac{\varepsilon}{2} |\nabla \phi|^2 \right)}_{\text{fracture energy}}$$

*fractured area*

**Evolution Equations**

$$\nabla \cdot \left( \frac{\partial \Psi(E, \phi)}{\partial E} \right) = 0$$
$$\frac{\partial \phi}{\partial t} + M \left( \frac{\partial \Psi(E, \phi)}{\partial \phi} + \nabla \cdot \frac{\partial \Psi(E, \phi)}{\partial \nabla \phi} \right) = 0$$

# Pros vs Cons

Avoid explicit tracking of interface ✓  
Can handle complex geometries and topology changes ✓  
The phase-field encodes the physics ✓

Dimension increase  
Sharp gradients

Computational cost ✗  
Parameter choice ✗

# Take Home Message

## Consider phase-field models when:

1. Evolving complex interfaces
2. Multiphysics, different energy contributions

## Remember:

1. The regularization parameter is important
2. Phase-field comes with computational cost  
(most of times it will pay off)